



RN-8201

B. E. - II (Sem. - IV) (Elect./EC/IC) Examination
May / June - 2010
Control Theory
(New Course)

Time : 3 Hours]

[Total Marks :

Instructions :

(1)

नीचे दशांशिक निशानीवाणी विगतो उत्तरवही पर अवश्य कभवी. Fillup strictly the details of signs on your answer book.	Seat No. :
Name of the Examination :	<input type="text"/>
<input type="text" value="B. E. - 2 (SEM. - 4) (ELECT./EC/IC)"/>	<input type="text"/>
Name of the Subject :	<input type="text"/>
<input type="text" value="CONTROL THEORY (NEW)"/>	<input type="text"/>
Subject Code No. : <input type="text" value="8"/> <input type="text" value="2"/> <input type="text" value="0"/> <input type="text" value="1"/>	<input type="text"/>
Section No. (1, 2,.....) : <input type="text" value="1&2"/>	
	Student's Signature

- (2) Answer all the questions.
- (3) Use semilog / graph papers wherever necessary.
- (4) Assume suitable data wherever necessary.
- (5) Figures to the right indicate full marks.

SECTION - I

- 1 (a) Attempt the following :
 - (i) The time needed for the response to reach 50% of the final value is termed as peak time. (True/false) 1
 - (ii) The response of the second order control system subjected to unit step input at $\rho = 1$ is _____ 1
 - (iii) Define open loop control system and closed loop control system. 2
 - (iv) With reference to state space representation of 2

the equation $\frac{d^2 y(t)}{dt^2} + 2 \frac{dy(t)}{dt} + 3y(t) = u(t)$ the

matrices A and B are.

- (v) Draw the signal flow graph for the block diagram of system shown in **fig. 1**. 1

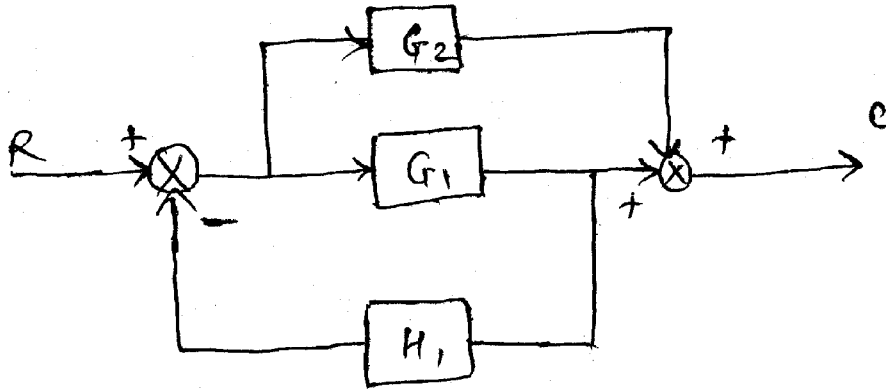


Fig. 1

- (vi) Define signal flow graph. 1
- (vii) Define transfer function. 2
- (b) Determine the overall transfer function $c(S)/R(s)$ for the system represented by the block diagram shown in **fig. 2**. 10

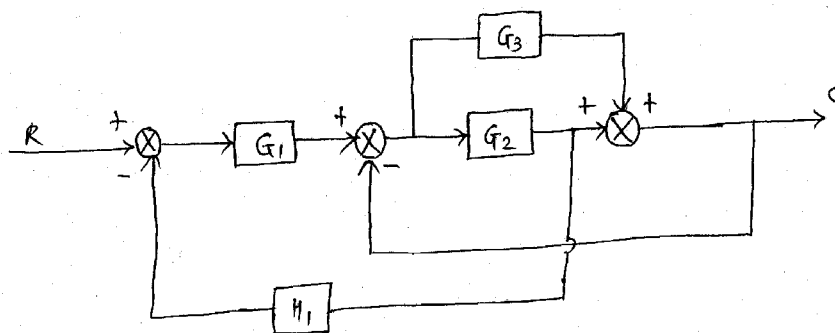


Fig. 2

- 2 (a) Obtain the transfer function $X_0(S) / X_1(S)$ for the mechanical system shown in **fig. 3**. 10

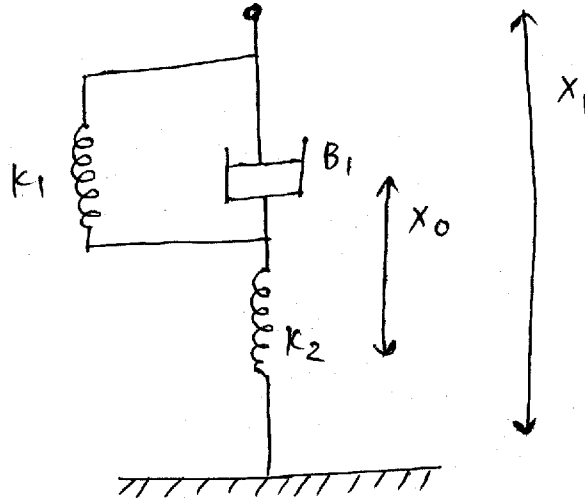


Fig. 3

- (b) Explain the Mason's gain formula to obtain the transfer function of the system from SFG. 5

OR

- 2 (a) Obtain the state equation for the differential equation given by 8

$$\frac{d^2y}{dt^2} + 3\frac{dy}{dt} + 4y = \frac{du}{dt} + 3u$$

- (b) Derive the expression for the unit step response of second order system with constant oscillators. 7

- 3 Attempt any **three** out of the following : 15

- (i) Explain the rise time, peak time, peak overshoot, and settling time to the second order under damped system subjected to unit step input signal.

(ii) For the given transfer function $\frac{C(S)}{R(S)} = \frac{K}{S^2 + KK, S + K}$

determine the value of K and K_1 , so that the maximum overshoot in unit step response is 25 per cent and peak time is 2 second.

(iii) Determine the overall transfer function C/R for the signal flow graph shown in **fig. 4**.

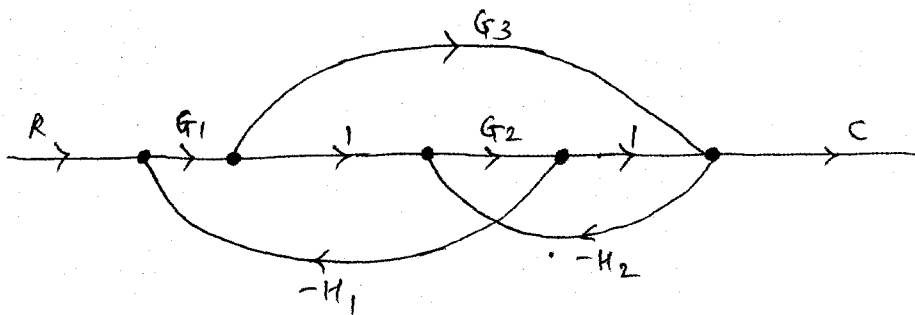


Fig. 4

(iv) Determine the overall transfer function for the block diagram shown in **fig. 5**.

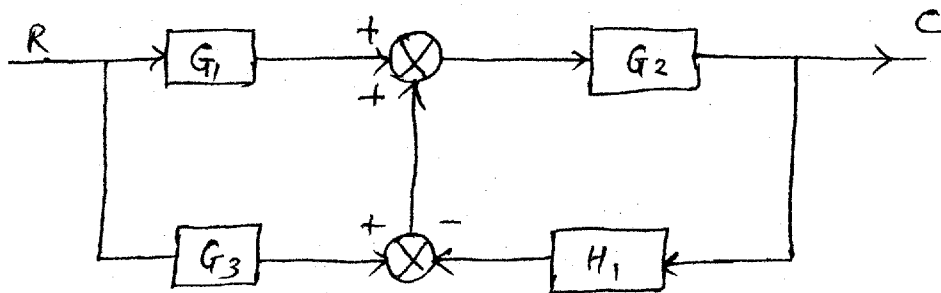


Fig. 5

(v) For the second order control system $\rho = 0.6, w_n = 5 \text{ rad/sec}$ obtain the values t_r, t_p, M_p, t_s subjected to unit step input signal.

SECTION - II

- 4 (a) Fill in the blanks : 5
- (i) The frequency at which Nyquist diagram crosses the negative real axis is known as _____.
 - (ii) Routh Hurwitz criteria is a _____ domain approach.
 - (iii) Root locus ends at zero. At every zero value of K is _____.
 - (iv) The slope of the magnitude curve of the Bode Plot of G (jw) at the gain crossover usually given an indication of _____ stability. (relative/absolute)
 - (v) In a linear system if output approaches infinity, the system is _____.
- (b) True/False questions : 5
- (i) Relative stability can be obtained from R H Criteria.
 - (ii) If any odd or even power of 's' is present in system characteristic equation polynomial, then system has sustained oscillation.
 - (iii) M and N circles are applicable to non unity feedback system.
 - (iv) When one or more non repeated roots of the system are on imaginary axis then system is marginally stable.
 - (v) If there are three zeros and two poles of GH(S), then there will be three root loci.
- (c) Discuss the stability of the system whose 4
characteristic equation
$$S^6 + 2S^5 + 8S^4 + 12S^3 + 20S^2 + 16S + 16 = 0$$

- (d) Determine the range of K for the system to be stable 4
 $S^4 + 5S^3 + 5S^2 + 4S + K = 0$
- (e) Write down the limitation of Hurwitz's Criterion. 2
- 5 (a) Discuss in brief procedure of obtaining Nichol's Chart 6
 from N-circles and M circles.
- (b) A unity feedback system has a frequency transfer 9

$$\text{function } G(S) = \frac{10}{S(1+0.1S)(1+0.5S)}$$

Plot the necessary data of this system on Nichol's chart and hence obtain the following :

- (i) phase margin and gain margin
 (ii) Gain and phase cross over frequencies
 (iii) Bandwidth

OR

- 5 (a) State the frequency domain specification and explain 6
 their correlation with the time-domain specifications.
- (b) Draw the bode diagram of the open loop transfer 9

$$\text{given as } G(S) = \frac{64K(S+2)}{S(S+0.2)(S^2+3.2S+64)}$$

- (i) Determine gain margin, phase margin and the corresponding cross over frequencies with $K = 1$.
 (ii) Determine gain margin and phase margin for $K=10$.

- 6 (a) For a unity feedback control having open loop transfer function 7

$$G(S) = \frac{10(S+0.5)}{S(S-1)(S+2)}$$

Draw the Nyquist plot and hence comment on the stability of the system.

- (b) The open loop transfer function of a unity feedback control systems is given by : 6

$$G(S) = \frac{(S+2)}{(S+1)(S-1)}$$

Using Nyquist criterion check the system stability.

- (c) Define gain margin and phase margin with respect to Nyquist plot. 2

OR

- 6 (a) Describe the all steps for constructing Root Locus. 7

- (b) Draw the shape of root locus for the open loop transfer function. 8

$$G(S)H(S) = \frac{K}{S(S+4)(S^2+4S+8)}$$
